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### The von Neumann Computer Model

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# 1. The von Neumann Computer Model

• Von Neumann computer systems contain three main building blocks:

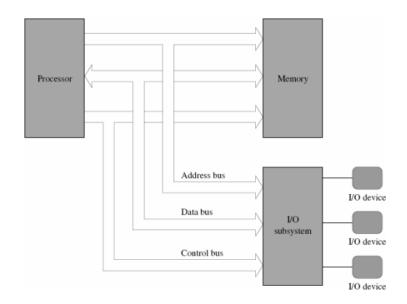
the central processing unit (CPU),

memory,

and input/output devices (I/O).

- These three components are connected together using the system bus.
- The most prominent items within the CPU are the registers: they can be manipulated directly by a computer program.

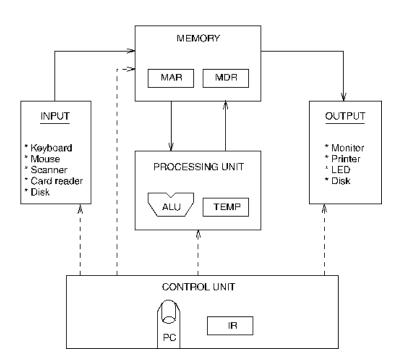
The following block diagram shows major relationship between CPU components:



#### 2. Components of the Von Neumann Model

- 1. Memory: Storage of information (data/program)
- 2. Processing Unit: Computation/Processing of Information
- Input: Means of getting information into the computer. e.g. keyboard, mouse
- 4. **Output**: Means of getting information out of the computer. e.g. printer, monitor
- Control Unit: Makes sure that all the other parts perform their tasks correctly and at the correct time.

The von Neumann Machine:



## 3. Communication Between Memory and Processing Unit

Communication between memory and processing unit consists of two registers:

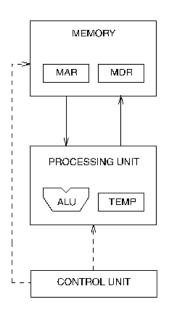
- Memory Address Register (MAR).
- Memory Data Register (MDR).

#### To read,

- 1. The address of the location is put in MAR.
- 2. The memory is *enabled* for a read.
- 3. The value is put in MDR by the memory.

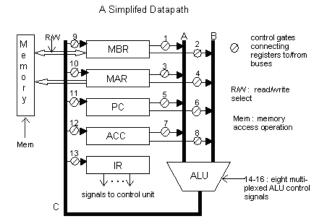
#### To write,

- 1. The address of the location is put in MAR.
- 2. The data is put in MDR.
- 3. The **Write Enable** signal is *asserted*.
- 4. The value in MDR is written to the location specified.

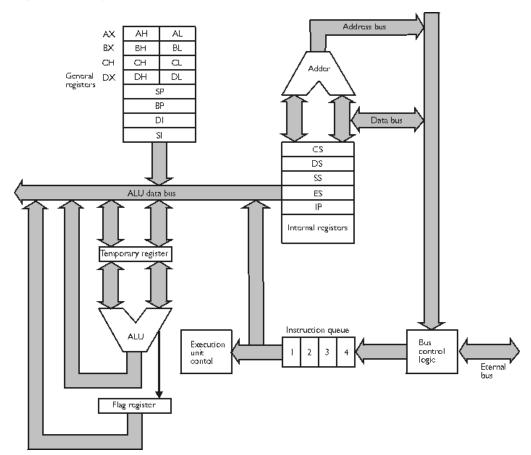


#### 4. CPU data-path

- Hardware units like ALU's, registers, memory, etc., are linked together into a data-path.
- The flow of bits around the data-path is controlled by the "gates" which allow the bits to flow (on) or not flow (off) through the data-path.
- The binary instructions (1 = on; 0 = off) that control the flow are called *micro-instructions*.



#### Simplified x86 data path:

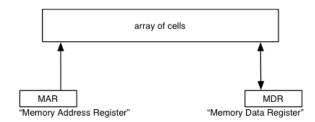


## **5. Memory Operations**

• There are two key operations on memory:

Memory Operations:

- fetch( address ) returns value without changing the value stored at that address.
- store(address, value) writes new value into the cell at the given address.
- This type of memory is random-access, meaning that CPU can access any
  value of the array at any time (vs. sequential access, like on a tape).
- Such memories are called RAM (random-access memory.)
- Some memory is non-volatile, or read-only (**ROM** or read-only memory.)



## fetch (addr):

- 1. Put addr into MAR
- 2. Tell memory unit to "load"
- 3. Memory copies data into MDR

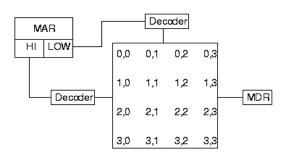
#### store (addr, new-value):

- 1. Put addr into MAR
- Put new-value into MDR
- 3. Tell memory unit to "store"
- 4. Memory stores data from MDR into memory cell.

#### 6. Understanding the MAR and the MDR

- MAR stands for memory address register:
  - MAR is connected to the address bus.
  - MAR is "the only way" for the CPU to communicate with address bus.
  - Tri-state buffer between MAR and the address bus prevents MAR from continously dumping its output to the address bus.
  - MAR can hold either an instruction address or a data address.

#### Memory Circuitry:



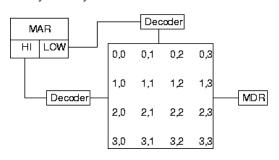
### 7. Understanding the MAR and the MDR, Cont.

- MDR Stands for memory data register.
  - MDR is connected to the data bus.
  - Data can go in both directions: to and from memory,

therefore, MDR can load its data from

- the data bus (for reading data)
- one of the CPU registers (for storing data.)
- A 2-1 MUX circuit selects input from one of the two.

Memory Circuitry:



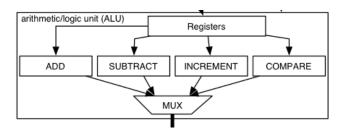
More info: von Neumann Architecture article by Prof. Fabio Pellacini, Dartmouth College, NH.

#### 8. ALU, the Processing Unit

- Processing unit is hardware that implements Arithmetic and Logical Operations.
- ALU stands for Arithmetic and Logic Unit, capable of performing

```
ADD, SUBTRACT, AND, OR, and NOT operations.
```

#### The ALU:



- The size of input quantities of ALU is often referred to as word length of the computer.
- Many processors today have word length of 32 and 64 bit.
- Processing unit also includes a set of registers for temporary storage of data and memory addressing.

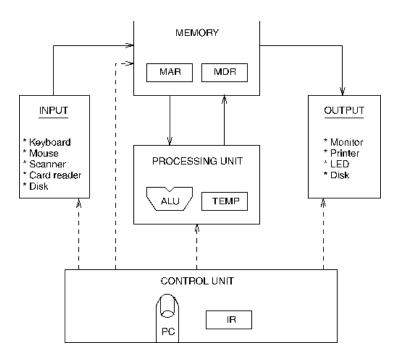
## 9. ALU and the Word Length

- The size of quantities processed by ALU is the word length of the computer.
- The word length does not affect what a computer can compute.
- A computer with a smaller word length can do the same computation as one with a larger word length...
  - ...but it will take more time.
- For example, to add two 64 bit numbers,

```
word length = 16 takes 4 adds.
word length = 32 takes 2 adds.
word length = 64 takes 1 add.
```

#### 10. Control Unit

- Manages the Precessing Unit.
- · Implemented as FSM.
- FSM directs all activity.
- Clock-based step-by-step precessing, cycle-by-cycle.
- FSM is controlled by the
  - 1. Clock signal
  - 2. Instruction Register
  - 3. Reset signal



### 11. Control Unit, Cont.

Control unit includes

- Instruction Register IR
- Instruction Pointier IP (aka Program Counter PC)

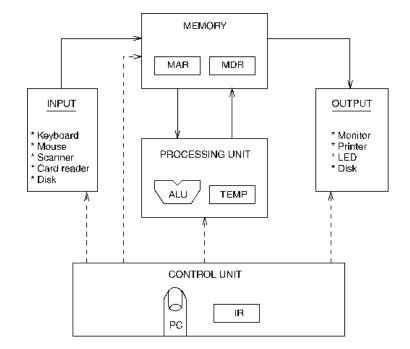
FSM outputs of the control unit,

\_ \_ \_ ->

shown by dash lines, have two purposes:

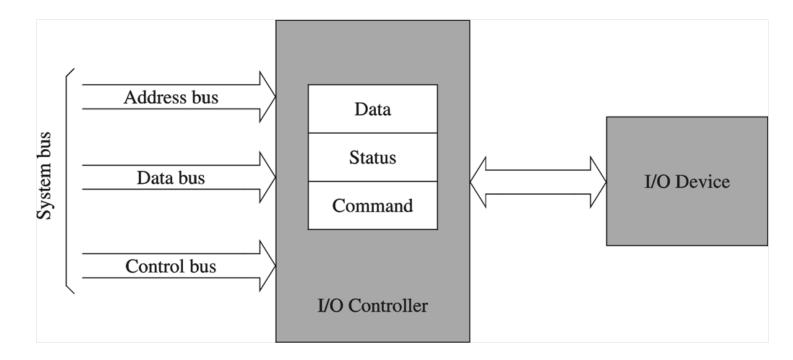
- 1. Control processing that takes place inside the ALU.
- 2. Authorize read/write gate control of the CPU data-path.

Control unit demo: <u>cjumpcxx.exe</u> -> CPU, memory, Assembly -> Protected memory.



## 12. Input/Output

- I/O controller provides the necessary interface to I/O devices.
- Takes care of low-level, device-dependent details.
- · Provides necessary electrical signal interface.



### 13. Input/Output Ports

- Processor and I/O interface points for exchanging data are called I/O ports.
- Two ways of mapping I/O ports:

#### 1. Memory-mapped I/O:

- I/O ports are mapped to the memory address space.
- Reading/writing I/O is similar to reading/writing memory.
- Can use memory read/write instructions.
- Motorola 68000 uses memory-mapped I/O.

#### 2. Isolated I/O:

- Separate I/O address space.
- Intel 80x86 processors support isolated I/O.
- Requires special I/O instructions, like IN and OUT on x86.

### 14. Input/Output Address Space

- Pentium x86 provides 64 KB of I/O address space.
- Can be used for 8-, 16-, and 32-bit I/O ports.
- Combination cannot exceed the total I/O address space, can have either
  - o 64 K 8-bit ports
  - o 32 K 16-bit ports
  - o 16 K 32-bit ports

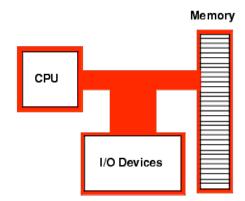
- A combination of these for a total of 64 KB.
- I/O instructions do not go through memory segmentation or paging.
- I/O address refers to the physical I/O address.

### 15. Console Input/Output in Protected Memory Mode

- Using console in Protected Memory Mode:

  - Keyboard input
  - Console display output
  - · Ascii character encoding

Von Neumann Computer System Block Diagram:



#### 16. Instruction Processing

Central idea of von Neumann model is that both program and data stored in computer memory:

- Program is a sequence of instructions
- Instruction is a binary encoding of operations and operands:
- For example, an arithmetic expression

$$-a + b * c$$

could be computed by a program with three machine instructions

```
neg ax ; negate (multiply by -1)
imul bx, cx ; multiply and store result in bx
add ax, bx ; add and store result in ax
```

where NEG, IMUL, ADD are arithemtic instructions, AX, BX, and CX are operands.

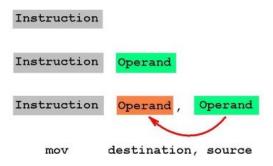
- o Instructions are most basic units of processing.
- Instructions are executed under control of the control unit.

### 17. Instruction Components

- Instruction in memory has two parts: opcode and operands.
- The opcode identifies the operation that instruction does
- The operands are subjects of the operation, such as data values, registers, or memory addresses.

Instruction formats:

- Due to variety of opcodes and operands, instructions may occupy different sizes of bytes in memory.
- Instructions with no operands can have implied operands, those that are not explicitly shown.



#### 18. Why Learn Intel x86 ISA?

- The x86 Intel CPU family is generally classified as a Von Neumann Architecture Machine.
- Most pervasive ISA in the marketplace.
- · Opcodes have zero or more operands.
- Instructions and operands have strong support for data types.
- All x86 Assemblers are free, including Microsoft Macro Assembler, <u>MASM</u>.
- Fullscreen 32-bit debuggers WinDbg, OllyDbg, and MS Visual Studio.

## 19. Design of the x86 CPU Instruction Set

- Instruction set architecture (ISA) is an important design issue for CPU designers:
  - caches, pipelining, superscalar implementation can be added to the design later, but

it is very difficult to change the CPU instructions once in production and people writing software...

- ...LOOP instruction on the x86 CPU sees very little use in modern high-performance programs.
- Challenges:
  - Expandability is a big concern (predicting future needs.)
  - Legacy support is almost the opposite of expandability.
- Each instruction requires some number of transistors on the CPU's silicon die.

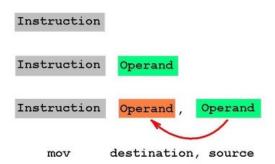
#### 20. CPU Instruction Set

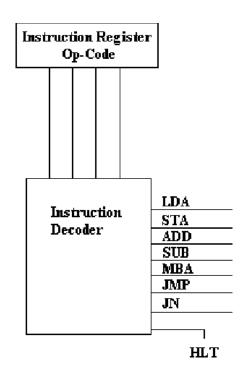
• A typical Von Neumann architecture encodes CPU instructions as numeric values in memory.

Instruction decoder:

- Programming and engineering of the *instruction set* is a major task in the CPU design.
- Each instruction needs a unique numeric opcode.

Instruction formats:





#### 21. History of IBM PC

- Design a simple instruction set to begin with and leave room for later expansion main reason the x86 is so popular and long-lived.
- Intel started with a relatively simple CPU and figured out how to extend the instruction set to accommodate new features.
- IBM decided that open documentation is a good thing.
- IBM published the <a href="IBM PC">IBM PC</a> Technical Reference Manual, with everything the engineers knew about the machine, which was another reason for the success of the IBM PC platform.
- See also: 25 Years of the IBM PC and CNN article Meet the inventor of Ctrl-Alt-Delete

#### 22. Early x86 Processor Family

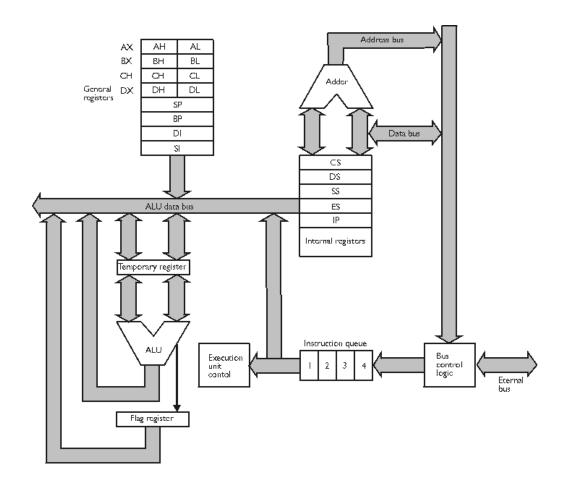
- Intel introduced microprocessors in 1969: 4-bit microprocessor 4004.
- 8-bit microprocessors are 8080 and 8085 models.
- 16-bit processors:
  - o 8086 introduced in 1979.
  - o 20-bit address bus, 16-bit data bus.

(8088 is a less expensive version.)

- Uses 8-bit data bus.
- Can address up to 4 segments of 64 KB.
- Referred to as the real mode addressing.
- Still fully compatible with modern x86 chips.

#### 23.8086 and 8088 CPU

- Year 1979
- The 8088, 8086, and 80286 are 16-bit CPUs.
- Internal registers are 16 bits in size.
- The 8086 is faster than the 8088 because of its 16-bit data bus; the 8088 has only an 8-bit data bus.
- The 16-bit data bus allows you to use EVEN and ALIGN on an 8086 processor to word-align data and thus improve data-handling efficiency.
- Memory addresses on the 8086 and 8088 refer to actual physical addresses.
- The 8086 and 8088 have 20 address pins, and 1 megabyte of addressable memory (which is the real mode segmented memory explained later) requires addresses of 20 bits in size.
- See also: <u>Brief History of Microprocessors</u>



#### 24.80186 CPU

- A faster version of 8086.
- 16-bit data bus and 20-bit address bus.
- Improved instruction set.

#### 25.80286 CPU

- Year 1982.
- Introduced protected mode addressing.
- Enhanced with memory protection capabilities with some instructions to control protected mode.
- Runs faster.
- 24-bit address bus.
- 16 MB address space.

- Segmentation in protected mode is different from the real mode.
- Allows the operating system to run multiple processes at the same time.
- The 80286 was the minimum for running Windows 3.1 and higher.
- · Backwards compatible.

#### 26.80386 CPU

- Year 1985.
- The 80386 and many of its successors are 32-bit CPUs.
- Internal registers are 32 bits in size.
- Unlike its predecessors, the 80386 processor can handle both 16-bit and 32-bit data.
- Supports entire instruction set of 80286.
- Adds several new instructions as well.
- Software written for the 80286 runs unchanged on the 80386, but the chip is faster.
- The 80386 implements many new hardware-level features, including
  - o paged memory.
  - o segmentation can be turned off (flat model).
  - support for multiple virtual 8086 processes.
  - o addressing of up to 4 gigabytes of memory.
  - o specialized debugging registers.

#### 27.80386 CPU, Cont.

- 32bit operating systems such as Windows NT required 80386 or higher processor.
- More embedded systems nowdays use the 80386 CPU.
- Examples include:
  - o high speed data communications devices.
  - o graphics equipment.
  - o tra-high-speed data acquisition gear.
  - o Cockpit displays of some modern jetliners use 80386 as controllers.
- See also: Intel 386 Manuals

#### 28.80486 CPU

- Year 1989.
- The 80486 processor is an enhanced version of the 80386 with
  - o instruction pipelining allows parallel execution capability to instruction decode and execution units.
  - o executes many instructions 2-3 times faster.
  - o achieves scalar execution of 1 instruction per clock cycle.

- The chip incorporates
  - o math coprocessor for performing floating-point arithmetic
  - 8 Kilobyte memory cache.

(The math coprocessor was disabled on a variation of the chip called the 80486SX.)

- New instructions.
- Fully compatible with 80386 software.
- Later versions introduced energy savings for laptops.
- See also: Intel 486 Manuals

#### 29. Pentium (Intel 80586)

• Pentium was introduced in 1993, followed by

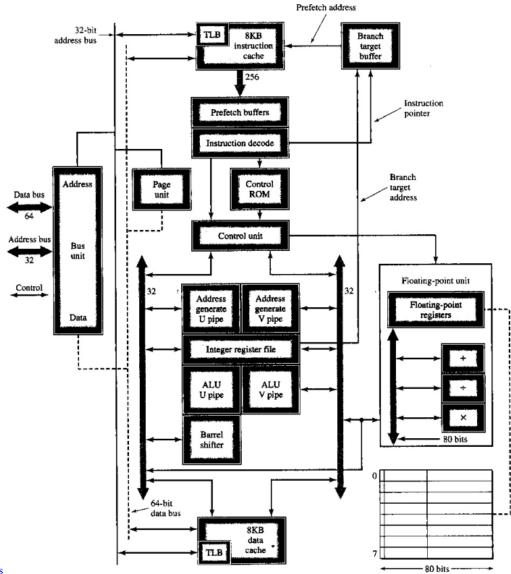
Pentium Pro in 1995,

Pentium II in 1997,

Pentium III in 1999,

Pentium IV 2001.

- Similar to 80486 but with 64-bit data bus.
- Wider internal datapaths: 128- and 256-bit wide.
- Added second execution pipeline.
- Superscalar performance allows two instructions per clock cycle.
- Doubled on-chip level-1 cache:
  - o one 8 KB for data
  - o another 8 KB for instructions.
- Added branch prediction.



• See also: Pentium Manuals

### 30. Pentium Pro

- Introduced in 1995.
- Three-way superscalar performance, 3 instructions per clock cycle.
- 36-bit address bus.
- 64 GB address space.
- Introduced dynamic execution:
  - o Out-of-order execution.
  - o Speculative execution.
- In addition to the level-1 cache, has 256 KB level-2 cache.

#### 31. Pentium II

- Introduced in 1997.
- Added multimedia (MMX) instructions.
- Doubled on-chip level-1 cache:
  - o 16 KB for data
  - 16 KB for instructions.
- Introduced comprehensive power management features:
  - o Sleep
  - o Deep sleep.
- In addition to the level-1 cache has 256 KB level-2 cache.

## 32. Itanium processor

• RISC design

(All previous x86 designs were CISC.)

- 64-bit processor
- Uses 64-bit address bus
- 128-bit data bus
- Introduced several advanced features:
  - Speculative execution
  - o Predication to eliminate branches
  - Branch prediction