Information Retrieval in Distributed Hypertexts

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Abstract

Hypertext is a generalization of the conventional linear text into a non-linear text formed by adding cross-reference and structural links between different pieces of text. A hypertext can be regarded as an extension of a textual database by adding a link structure among the different text objects it stores. We present a tool for finding information in a distributed hypertext such as the World-Wide Web (WWW). Such a hypertext is a distributed textual database in which text objects residing at (the same and) different sites have links to each other. In such a database retrieval is limited to the transfer of documents with a known name. Names of documents serve as links between different documents, and finding such references names is only possible by parsing documents that have embedded links to other documents.

Full-text search in such hypertexts is not feasible because of the discrepancy between the large size of the hypertext and the relatively low bandwidth of the network. We present an information retrieval algorithm for distributed hypertexts, which does an incomplete search through a part of the hypertext. Heuristics determine the selection of the documents that are to be retrieved and searched. A prototype implementation for the WWW, on top of Mosaic for X, is being used by an increasingly large user base.

1 Introduction

A simple definition of hypertext (mostly taken from [9]) is a database of (textual) information fragments (nodes) that has active cross-references (links) and allows the reader to “jump” to other parts of the database as desired. Most hypertext systems have a limited view on the jumps the reader may desire. Links are hard-wired, and the only jumps that are allowed are following links, backtracking, and maybe also jumping to the first node or to a node that appears in a history list or a hotlist.

Full-text search and/or the creation of indexes are only feasible when the hypertext system controls the entire hypertext, e.g. when the hypertext is contained in a (local) database or in files in a specific directory (tree). Intermedia [11], HyperNews [1], Superbook [6] and many others offer querying and information retrieval on the entire hypertext. The answers can be a list of relevant nodes, possibly annotated by a relevance score, or a graphical overview of the hypertext structure in which the relevant nodes are highlighted. An interesting variation in [7] presents the result of a search as a guided tour, generated by using the relevance scores and the link types.
In this paper we concentrate on distributed hypertexts such as the World-Wide Web. Unlike the distributed hypermedia storage system described in [8], the computer systems carrying the parts of the World-Wide Web are only loosely coupled, somewhat like heterogeneous multidatabase systems (but without a database scheme and without a DBMS). Each site is completely autonomous, and offers a simple interface (protocol) to the other sites. Hypertext nodes (often called documents) have a unique name, which combines information on the site, the protocol to be used to access the node, and the pathname within the site. Such a name is called a Universal Resource Locator (URL). In general the only service one may expect from a site is that when it is given a URL of an existing document it will return that document.

Finding information in such a distributed hypertext can only be done by means of (automated) browsing. Assuming that the hypertext is connected and that a good starting point can be found it is theoretically possible to simply retrieve all the static nodes and determine their relevance to a given expression, set of keywords, or other query. However, the size of a distributed hypertext such as the World-Wide Web is such that, given the current wide-area network infrastructure, such a search would take days, if not weeks, depending on the network load and on the availability of all the sites. Also, since these large hypertexts contain information on a wide variety of subjects, most of the time would be spent retrieving irrelevant documents. Furthermore, the Web contains computed nodes, that change very often, possibly depending on arguments given in the command to retrieve them. Some attempts have been made to create databases that can be used for retrieving information in the World-Wide Web. However, these “indexes” do not contain all information of the World-Wide Web. They can be used to retrieve documents based on title, citations and other preprocessed material. Furthermore, the creation and updates to these databases take a very long time, hence they are always out of date.

We present an automated browsing algorithm that tries to find some of the nodes that are relevant for a given query. The heuristics of this algorithm are based on a number of experiments related to finding the optimal browsing strategy, depending on the time or number of nodes one can visit, on the browsing facilities offered by the hypertext system, and of course on the structure of the hypertext itself. Several databases and facilities exist to find all nodes that satisfy a certain limited condition. Our algorithm tries to find some nodes quickly, satisfying any kind of condition the user may want (and provides a filter for). The answer of a query is always incomplete and non-deterministic, and it depends on the starting point (node) given to the browser. The algorithm has been implemented on top of the popular WWW browser “Mosaic for X”. An early prototype of this implementation, before the current heuristics were developed, was demonstrated at the 1993 ACM Conference on Hypertext.
# Browsing Techniques

Browsing is mostly influenced by the following three factors:

- the structure of the hypertext;
- navigational aids (hotlist, history, bread crumbs, fish-eye views, etc.);
- the navigational strategy of the user (e.g. breadth first or depth first).

In [2] a method is given to reduce the structure of a hypertext to a hierarchy (or set of hierarchies) and a set of cross-reference links. The basic idea is that from the user’s point of view a hypertext appears to have a hierarchical structure which is “disturbed” by some cross-reference links. In a (strict) hierarchy the reader is unlikely to get lost. The “amount” of disturbance generated by the cross-reference links is measured using two metrics, compactness and stratum. Compactness measures how many links one must follow (on average) to move between two arbitrary nodes. Stratum measures the amount of “reading order” in a hypertext.

In [3] navigation efficiency (or difficulty) is measured when taking into account different navigation aids offered by hypertext systems. Getting from one node to another becomes easier when history lists and/or hotlists are available. Marking nodes that have been visited before with so-called “bread crumbs” (from the fairy tale…), or marking links leading to them, helps avoiding going in the same direction twice. These facilities cannot simply be modeled by adding extra links to the hypertext in order to calculate their effect on the metrics or to count the number of cross-reference links they would generate. In [3] a large number of experiments (with simulated users) were conducted in order to find the influence of navigation aids on browsing.

The order in which the user visits nodes determines the number of links that must be followed in order to visit a given number of nodes, because links may have to be followed again or backwards in order to reach the desired nodes. Also, the order determines which links the user perceives as being structural (hierarchical) links and which links appear to be cross-reference links. In [3] different browsing strategies, ranging from breadth-first to depth-first have been evaluated. The hypertexts that were used in the experiments included those of the work of Erica de Vries [4, 5] and the book [9] by Shneiderman and Kearsley, as well as some artificially generated structures. The conclusion in [3], which is crucial for the algorithm we present is:

*For all hypertext structures, and for all kinds of navigational aids or combinations thereof, the depth-first navigation strategy is most effective in finding cross-reference links and in traversing a hypertext in as few steps as possible.*

The only exception to the above conclusion was that in very short browsing sessions, breadth-first navigation may be more effective in finding cross-reference links than depth-first. However, in this paper we assume that the (automated) browsing session is always long enough to benefit most from a depth-first strategy. In the next section we shall explain why finding a large number of cross-reference links is important.
The algorithm we present in section 3 uses a depth-first search because of the above conclusion. A breadth-first search tries to span the whole hierarchy, thus spending as much time scanning whole parts of the hypertext that contain no relevant information. A depth-first search finds a “sparse” subset of the hypertext. Assuming that relevant nodes occur in clusters, one is more likely to encounter nodes from relevant clusters by means of the sparse search than by an exhaustive search that never gets far away from the starting point in a reasonable amount of time.

3 A Navigational Algorithm: the “Fish-Search”

The main problems in performing information retrieval on a distributed hypertext are:

- finding a good starting point for the search;
- finding the “optimal” order in which to retrieve nodes.

Our algorithm only deals with the second point. Databases such as “The JumpStation”¹ or “The World-Wide Web Worm”² can be used to find documents that seem to be relevant based on a header, title or citations. But even more important than a starting point which is relevant to the search one wants to perform is a starting point that is “well connected”, meaning that from the starting point many sites that participate in the distributed hypertext are easily reachable. Existing tools do not support finding such well connected starting points.

Our search algorithm is based on the schools of fish metaphor: A school of fish moves in the direction of food. While swimming, the fish also breed. The number of children and their strength depends largely on the amount of food that is found. The school regularly splits into parts, when food is found in different directions. Individual fish or parts of the school that go into a direction in which no food is to be found will die of starvation. Fish or parts of the school that enter polluted waters also die.

When explaining the algorithm we will frequently refer to the metaphor.

Our Search Algorithm makes the following assumptions:

1. It is impossible to perform a complete search in a reasonable amount of time.

2. The relative cost (time/size) for retrieving a document is more or less constant for each site, but may differ significantly from site to site; the retrieval time is always an order of magnitude longer than the time to actually scan the document for information, regardless whether it is a keyword (or full-text) search, (approximate) regular expression search or a search using any kind of information filter.

3. Nodes that are relevant are usually clustered (meaning there is food for a number of fish, not just a single one).

¹The JumpStation can be found at http://www.stir.ac.uk/jsbin/js
²The Worm can be found at http://www.cs.colorado.edu/home/mcbryan/WWW.html
4. Depth-first search is generally better than breadth-first, except when there is very little time [3]. (This means the school moves on, rather than staying in the same neighborhood for too long and risking to die of starvation.)

5. All nodes have a unique identification, called Universal Resource Locator (URL), which can be used to tell the hypertext system to retrieve the node with a given URL.

6. Repetitive access to the same remote site may overload or break the connection, so access has to be spread among sites (this is not really an assumption but an observation).

7. Accessing sites in parallel does not increase overall throughput, (or if it does it places an unacceptable load on the network).

8. There is always a “current” node from where the search starts.

Note that the assumptions 3, 4, 5 and 8 relate to the hypertext structure; assumptions 2, 6 and 7 relate to the distributed system and network; assumption 1 is simply a matter of size vs. network and computation speed.

A particularly important aspect is the choice of the navigation strategy. One could imagine that because of assumption 5 the navigation strategy would not be important in the search-algorithm because we assume that there is no overhead in navigating from one node to another node to which there is no direct link. However, since we cannot retrieve all nodes in the distributed hypertext, we need a strategy that selects an order of retrieval which provides a reasonable distribution of the nodes within the hypertext. In [3] the distribution of nodes is not measured directly but the number of cross-reference links that are discovered is measured instead. Each time a cross-reference link is found a “gateway” is discovered that leads to another part of the hypertext. Cross-reference links can exist between nodes on the same site and between nodes on different sites. Our algorithm favors links to different sites because of the penetration they provide into different parts of the hypertext, and also because successive network accesses should preferably not be concentrated on the same part of the network. The experiments in [3] show that depth-first navigation results in the discovery of the largest number of cross-reference links, regardless the structure of the hypertext or the navigation aids offered by the system.

The algorithm keeps a sorted list (of URL’s of nodes to retrieve). Sorting is based on the relevance of nodes and on the last-in first-out principle that generates depth-first navigation behavior. (This list represents the school of fish.) Each time a node is retrieved, the URL’s of the nodes to which the outgoing links point are added to this list, in a way we shall explain later. (This is the way the fish produce offspring.) When we say a “link” is added to the list we actually mean the URL of the node the link points to.

The algorithm can be influenced by the following parameters:

**width**: Some nodes have a large number of outgoing links. Checking all these links would hold up the search in the immediate neighborhood of that node. Therefore the number of links that will
be followed per node is limited to the value of \textit{width}. However, when a relevant node is found, we allow a few more links because of the assumption that relevant nodes are probably clustered. The links that are not selected are remembered in case we run out of links to be followed. (The width represents the number of children a fish produces. When the fish finds food it produces more offspring.)

\textbf{depth}: Large distributed hypertexts contain information on all kinds of subjects. Searching for a long time in a direction in which no relevant information is found should be avoided. The number of links that are followed in a row without finding any relevant information is limited to the value of \textit{depth}. (The depth is the lifetime of a healthy fish which doesn’t find food. When a fish finds food its offspring will consist of healthy fish which can survive longer without food.)

\textbf{rate}: A target rate (in bytes/sec) determines which network accesses are considered acceptable, and which are too slow to investigate thoroughly. The average data rate is remembered per site. Outgoing links to nodes on sites with a data rate higher than \textit{rate} are favored over links to sites with a low rate. (Slow links represent polluted water, in which the fish die faster and produce less offspring.)

The algorithm works as follows:

1. Initially the list is empty and there is a “current” node.

2. The current node is parsed to check whether it contains “relevant” information (keywords, regular expressions or other items one may wish to find). Also, the URL’s of the nodes that the outgoing links from the current node point to are extracted from the node contents.

3. A number of these links, determined by the \textit{width} parameter, are “selected” in the following way:

   - In case the current node is relevant these links are marked as \textit{child of a relevant node} and added to the front of the list, meaning they will be used first. If the current node is not relevant the links are added to the list, right after the last node that was marked as \textit{child of a relevant node}.
   - The links that are not selected are added to the end of the list. (They will only be used in case we run out of other links.)
   - The selection of links is not entirely random: links pointing to nodes on other sites are prefered, because following them generates a better distribution of nodes in the distributed hypertext.
   - The number of selected links is not simply equal to the value of \textit{width}. For a relevant node, more links are selected than \textit{width}. (In the implementation we use a factor of 1.5.) For a node which takes a long time to retrieve, fewer links than \textit{width} are selected in order to avoid spending a lot of time retrieving nodes from remote sites with a slow or erratic connection.
Also, links to nodes on sites with a connection faster than rate are preferred over links to nodes on sites with a slower connection.

- The links in the list have an associated depth. Each time a link is used, and the retrieved node is judged not to be relevant, its embedded links, to be added to the list, get a lower depth (previous depth — 1). When a link has depth 0, the URL's embedded in the retrieved node are discarded unless the retrieved node is relevant. When a relevant node is found, the embedded links get the depth specified by the depth parameter.

- Links (URL's actually) that already appear in the list are not entered a second time. If the new link should appear before the old one the old one is deleted, else the new link is not added. The depth of the link becomes the maximum of the two depths.

4. The list is searched to find the first link to a node which is located on a different site than the current node. If this link is among the first $3 \times width$ in the list, it is removed from the list and the node is retrieved. If not, the first link in the list is removed and that node is retrieved. The transfer-rate for this retrieval is measured and the average rate for this site is updated. The newly retrieved node becomes the “current” node, and the algorithm returns to step 2.

5. The algorithm stops when a specified amount of time has passed or when the list is empty.

4 A Searching Tool for the World-Wide Web

The algorithm described in the previous section can be used in any hypertext that is too large to do a full-text search and that cannot be indexed. However, the most straightforward application of the algorithm is its use for searching the World-Wide Web (WWW). The Web is quickly becoming the most popular, and maybe also the largest distributed hypertext, consisting of loosely coupled sites. The popularity of the WWW has really taken off since the public release of an excellent browsing tool by the National Center for Supercomputing Applications of the University of Illinois: Mosaic for X (later followed by Mosaic for Windows, for the Macintosh and for the Amiga). Since Mosaic for X is publicly available in source code format, we decided to integrate our navigational search algorithm into Mosaic for X. In Mosaic it is possible to retrieve documents by giving their URL. The links in the hypertext are only necessary to find URL's that probably exist. (Dangling links cannot be forbidden in a distributed hypertext such as the WWW.)

The fish-search for Mosaic provides three kinds of search operations:

**keyword search**: a set of words is given, and nodes are searched either for all words occurring together or simply for one or more of them (user selectable). The number of matches of each of the keywords,  

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3 At our site, win.tue.nl, the number of accesses to our Gopher server exceeded the accesses to our WWW server in the third quarter of 1993. Three months later, the accesses to our WWW server have gone up to 4 times the number of Gopher accesses.
increased when multiple keywords are found, but relative to the size of the node, determines the relevance of that node.

**regular expression search**: a regular expression is given (starts with `/`), and nodes are searched that match the expression. The number of matches, relative to the size of the node, determines the relevance of that node. The regular expression can be given in any syntax supported by the GNU regex library, used by our tool. Also, the syntax of agrep can be used, allowing a search for patterns with a configurable number of (spelling) errors. Agrep is described in [10].

**external filtering**: the name of an external program is given, which determines the relevance of a node and returns a number. By using this mechanism, Mosaic can be turned into an information retrieval engine for any kind of information for which the application programmer can write a filter without changing Mosaic in any way.

The *fish-search* uses the algorithm of section 3, except for the part that suggests taking the speed of the communication with a site into account. Widespread use of the *fish-search* poses a great risk of either saturating the Internet or discouraging its use because of poor performance. As a solution, a *caching server* was developed, called “Lagoon”, which eliminates repeated access to the same nodes. (The lagoon is a secluded part of the sea, (hopefully) containing non-polluted water, in which the fish are trapped.) Since Lagoon is transparent to Mosaic and to the user, accesses to nodes which are already in the cache cannot be distinguished from accesses that require a node to be retrieved over the Internet. Hence, the transmission speed can vary significantly between nodes from the same site.

The use of the fish-search in combination with Lagoon provides a search platform which is particularly suited for sites with a large number of users wanting to find very different kinds of information. We feel that finding *some* information on a *large number of topics*, or arbitrary regular expressions, or any kind of content-based selection one can implement, may be at lease as important than the ability to find *all* information for a *limited set of words or topics* or based only on titles or headers.

Figure 1 shows the current widget for specifying the search string and setting the options of the *fish-search*. Figure 2 shows a possible result of a search. The result can be saved as an annotation to the starting node, or can be mailed as an HTML document.

### 5 Conclusions and Future Work

An algorithm has been presented that performs a partial search through a distributed hypertext, based on heuristics that have been verified by a large number of simulations. The algorithm has been implemented on top of the popular “World-Wide Web” browser “Mosaic for X”. It turns the browser into an information retrieval tool for the World-Wide Web, based on searching the contents (body) of the documents in the Web. As such, it complements the existing databases that provide indexes based on titles or headers of documents.

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4HTML is the language used in the WWW.
Figure 1: Fish-search setup widget

Figure 2: Fish-search result widget
The current algorithm only looks at the contents of individual nodes or documents. In the future we intend to expand the algorithm to allow searching for documents that not only satisfy given criteria on their content but also on their connection to each other. A document, not containing a given keyword, but leading to a large number of documents that do contain the keyword, may well be considered more relevant than the individual documents containing the desired keyword. Also, one may be interested in for instance only those documents on a certain topic that have an outgoing link to an audio or video fragment. Searching for such structural information in addition to the (textual) content is a topic of ongoing research.

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References


